

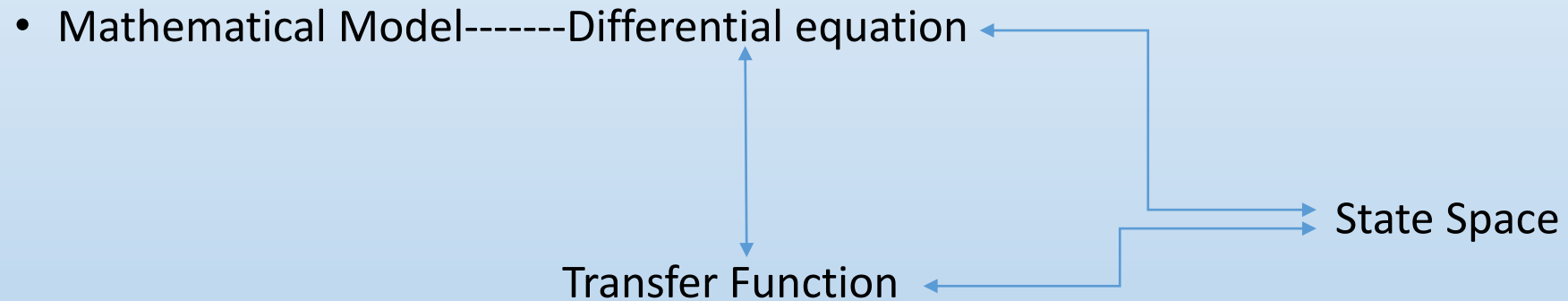
EEPC35-Control System-II

- **MOTIVATION, MODELLING OF DIGITAL CONTROL SYSTEMS**
 - Introduction to digital control
 - Mathematical models of discrete-time systems
- **DESIGN OF DIGITAL CONTROL ALGORITHMS**
 - Digital control design
- **CONTROL SYSTEM ANALYSIS AND DESIGN IN STATE-SPACE**
 - Introduction to state space model
 - Feedback control design
- **NONLINEAR SYSTEMS ANALYSIS**
 - Introduction to nonlinear systems
 - Stability analysis of nonlinear systems

DIGITAL CONTROL SYSTEMS

Brief of CS-I

- LTI Systems Continuous time



Representation----- a)Signal Flow Graph

b) Block Diagram

- Analysis of System

Main Concern Stability of the system

- Define Performance Specifications

- Time Domain

- ❖ Transient Region (Relative stability)

- ✓ Rise Time t_r

- ✓ Delay Time t_d

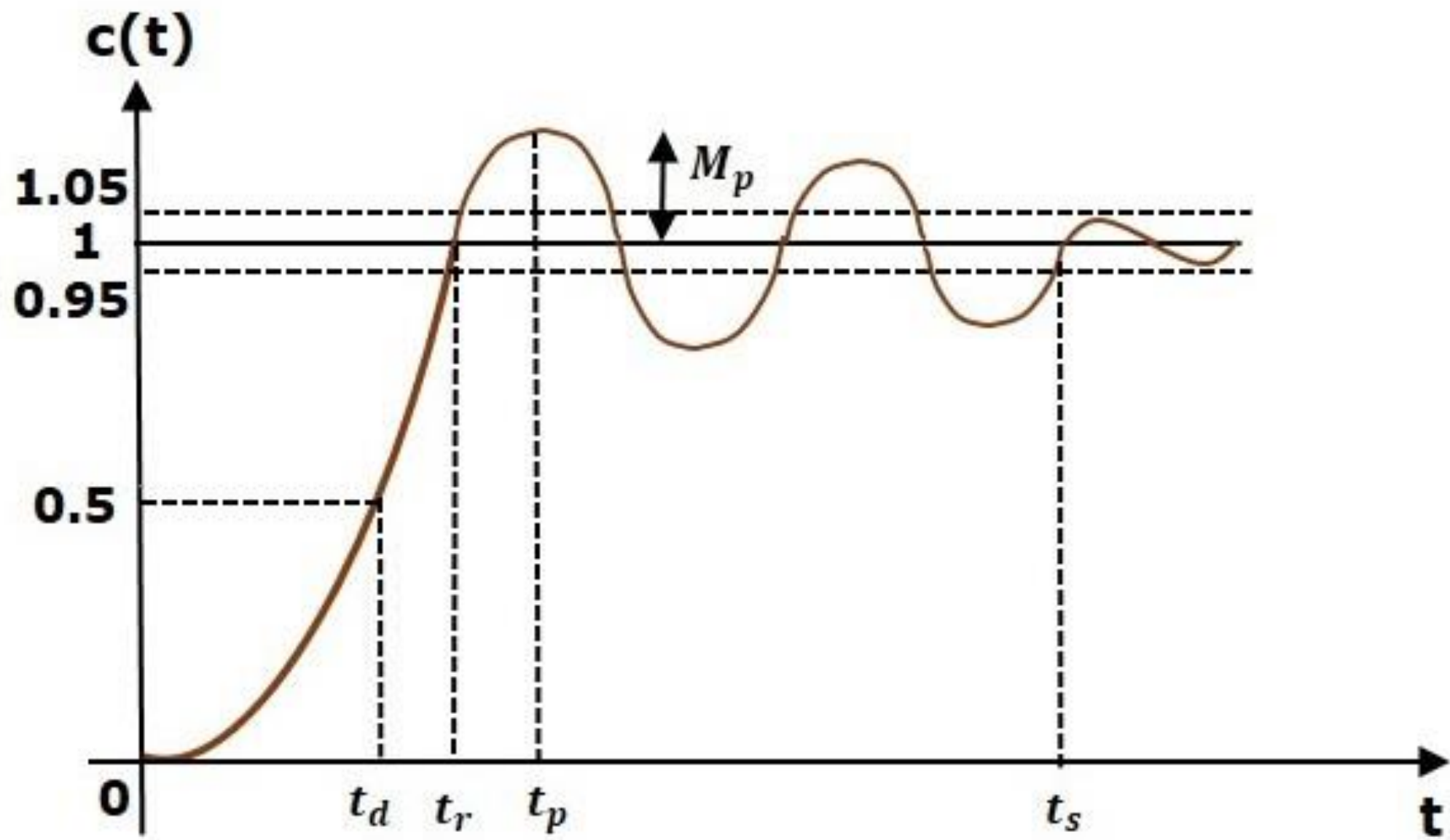
- ✓ Peak Time t_p

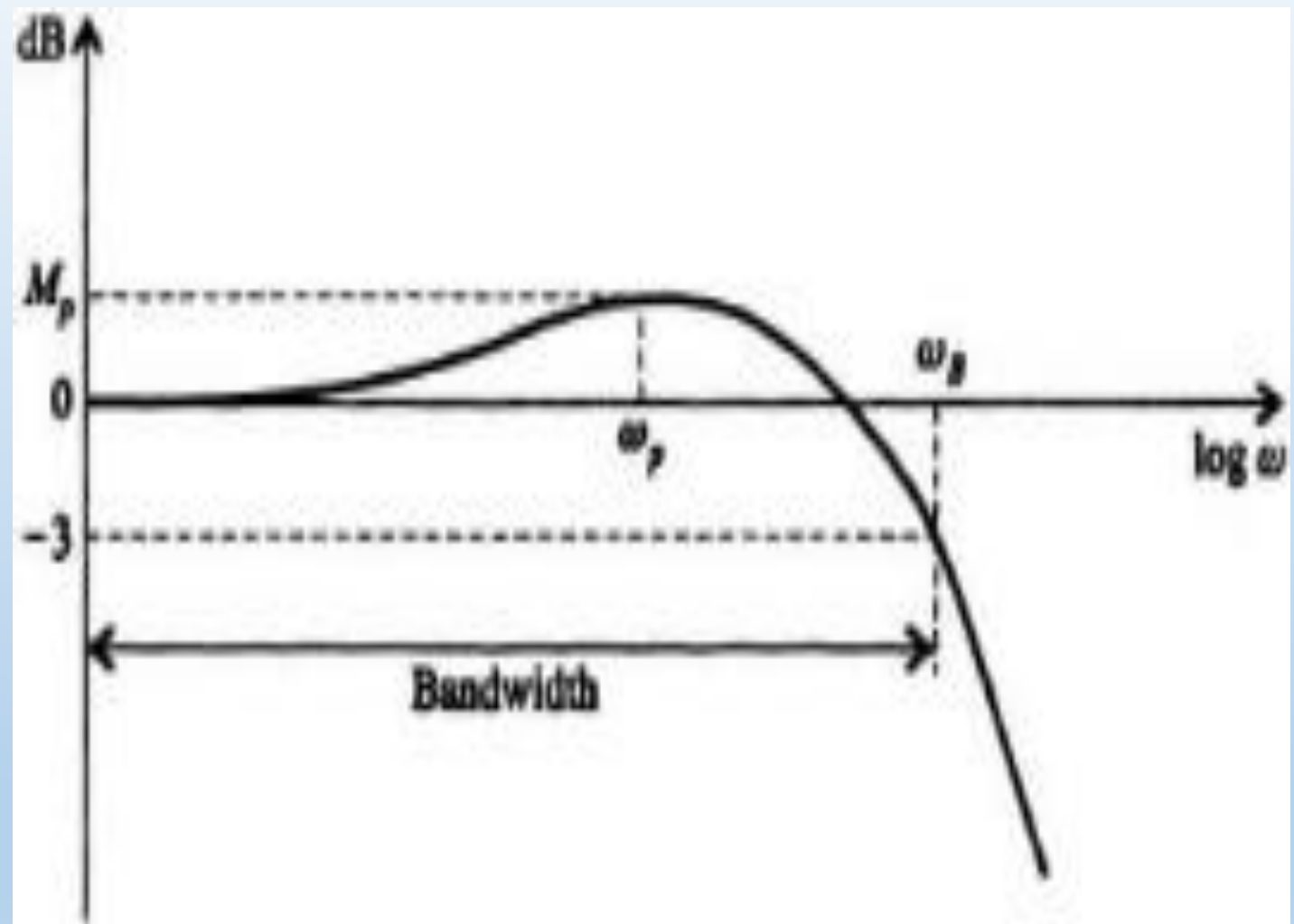
- ✓ Settling Time t_s

- ✓ Maximum Over shoot M_p

- ❖ Steady State Region (Accuracy)

- ✓ Steady state error e_{ss}





➤ Frequency Domain

❖ Closed Loop Performance Specifications

- ✓ Resonance Frequency ω_r
- ✓ Magnitude at resonance Frequency M_r
- ✓ Bandwidth BW ω_b
- ✓ Cutoff Rate

❖ Open Loop Performance Specifications

- ✓ Gain Margin (Gain at Phase crossover frequency)GM
- ✓ Phase Margin (Phase at Gain crossover frequency)PM ϕ_m

□ Time domain and Frequency domain specifications are related to each other e.g. $t_r \propto 1/\omega_b$

Methods to Analyze The System Stability

➤ Algebraic Methods

- ✓ Routh – Hurwitz criterion

- ✓ Liapunov's Criterion

➤ Algebraic + Graphical methods

- ✓ Nyquist Criterion (Frequency Domain)

➤ Graphical Methods

- ✓ Root Locus Method (s-Plane)

- ✓ Nichol's Chart (C.L.P Frequency Domain)

- ✓ M and N Circles (do)

- ✓ Bode Plots (O.L.P Frequency Domain)

Design To meet the Performance Specifications

- Achieve Stability (Add Zero)
- Achieve Accuracy (Add Pole)
- Achieve both of above(Add Both)

Root Locus/Bode Plot /State Feedback methodology can be used